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[ref] Understanding Machine Learning: From Theory to Algorithms, Shai Shalev-Shwartz and Shai Ben-David (2014)



# **Recall:**

No-free-lunch: there is no universal learner! PAC learning (**Provably Approximately Correct**): Introduce the prior knowledge via "realizable" over a function class.

Agnostic PAC learning: introducing the prior knowledge via adaptive loss.

# **Today's topic:**

We will give an example to show how to achieve PAC learnable : finite function class  $\mathcal{H}$  is PAC-learnable!





# PAC learning

DEFINITION 3.1 (PAC Learnability) A hypothesis class  $\mathcal{H}$  is PAC learnable if there exist a function  $m_{\mathcal{H}} : (0,1)^2 \to \mathbb{N}$  and a learning algorithm with the following property: For every  $\epsilon, \delta \in (0,1)$ , for every distribution  $\mathcal{D}$  over  $\mathcal{X}$ , and for every labeling function  $f : \mathcal{X} \to \{0,1\}$ , if the realizable assumption holds with respect to  $\mathcal{H}, \mathcal{D}, f$ , then when running the learning algorithm on  $\underline{m} \geq \underline{m}_{\mathcal{H}}(\epsilon, \delta)$  i.i.d. examples generated by  $\mathcal{D}$  and labeled by f, the algorithm returns a hypothesis h such that, with probability of at least  $1 - \delta$  (over the choice of the examples),  $L_{(\mathcal{D},f)}(h) \leq \epsilon$ .

 $m_{\mathcal{H}}(\epsilon, \delta)$ : sample complexity. Measure how many samples required to guarantee PAC (minimal). Informally, when  $m_{\mathcal{H}}(\epsilon, \delta) < \infty$ , we call a function class "PAC learnable".



### **Example: finite function class is PAC-learnable!**

COROLLARY 3.2 Every finite hypothesis class is PAC learnable with sample complexity  $\begin{bmatrix} \log(|\mathcal{H}|/\delta) \end{bmatrix}$ 

$$m_{\mathcal{H}}(\epsilon, \delta) \leq \left| \frac{\log(|\mathcal{H}|/\delta)}{\epsilon} \right|.$$

Hint: for a given **bad** function in  $\mathcal{H}$ , it predicts each data point correctly with probability  $\leq 1 - \epsilon$ . Therefore, for the training set with *m* samples, the training set has zero loss with probability  $\leq (1 - \epsilon)^m = e^{m \log(1 - \epsilon)}$ . That is to say:

a bad function has small probability to be chosen at the training phase.

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Using union bound over all the functions, the probability becomes  $\leq |\mathcal{H}|e^{m\log(1-\epsilon)} = e^{\log|\mathcal{H}|+m\log(1-\epsilon)}$ . To make the probability equal to  $\delta$ , we requires that  $\log |\mathcal{H}| + m\log(1-\epsilon) = \log \delta$ , leading to  $m = -\frac{\log \frac{|\mathcal{H}|}{\delta}}{\log(1-\epsilon)} \approx \frac{\log \frac{|\mathcal{H}|}{\delta}}{\epsilon}$ 

Formally, see Page 39 in the reference book.

#### 泛化理论

## **Take-away messages**

(a) Finite function class is PAC-learnable with 
$$m_{\mathcal{H}} = \frac{\log \frac{|\mathcal{H}|}{\delta}}{\epsilon}$$
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All the slides will be available at <u>www.tengjiaye.com/generalization</u> soon.

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# Thanks!



