

# 泛化理论

## 第三章 Stability

### §3.1.1 Stability-based Bound

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[ref] Bousquet, O., & Elisseeff, A. (2002). Stability and generalization. *The Journal of Machine Learning Research*, 2, 499-526.

[ref] Hardt, M., Recht, B., & Singer, Y. (2016, June). Train faster, generalize better: Stability of stochastic gradient descent. In *International conference on machine learning* (pp. 1225-1234). PMLR.

## Recall:

Uniform Convergence:  $L(\hat{f}) - \hat{L}(\hat{f}) \leq \sup_{f \in \mathcal{F}} |L(f) - \hat{L}(f)|$ .

Bad news: not algorithm-dependent; a loose bound...

## Today's topic:

**algorithmic stability**: another approach to generalization

## Algorithmic Stability

*Intuition on stability: similar datasets return similar models*

$\epsilon$ -Uniform-stability (not the unique definition):

If  $\mathcal{D} = \{z_1, \dots, z_n\}$  and  $\mathcal{D}' = \{z'_1, \dots, z_n\}$  differs with only one sample, and the algorithm  $\mathcal{A}$  satisfies:

$$\sup_z \mathbb{E}_{\mathcal{A}}[\ell(\mathcal{A}(\mathcal{D}); z) - \ell(\mathcal{A}(\mathcal{D}'); z)] \leq \epsilon,$$

then the algorithm is stable.

Note: the algorithm takes dataset as input and returns estimated parameter (or, model).

1. Sup on  $z$ : for any testing point  $\rightarrow$  uniform
2. Expectation on  $\mathcal{A}$   $\rightarrow$  random initialization, random operation ...
3. “similar” dataset  $\rightarrow$  the dataset has only one different example
4. “similar” model  $\rightarrow$  the model has similar *loss* on any testing point

## Stability and Generalization

*One sentence: algorithmic stability leads to generalization bound*

**Theorem (stability and generalization).** If the algorithm  $\mathcal{A}$  is  $\epsilon$ -Uniform-stable, its expected generalization gap (on parameter  $\hat{\beta} = \mathcal{A}(D)$ ) satisfies

$$\mathbb{E}_{D, \mathcal{A}} \mathbb{E}_L [L(\hat{\beta}) - \hat{L}(\hat{\beta})] \leq \epsilon,$$

where  $\mathbb{E}_L$  denotes the expectation on testing point, and  $\mathbb{E}_D$  denotes the expectation on training samples.

Note that different from previous analysis, here we use expectation form  $\mathbb{E}_D$  instead of the high probability bound (with high probability,  $\mathbb{E}_L [L(\hat{\beta}) - \hat{L}(\hat{\beta})] \leq \epsilon$ ).

We will talk about this in the following sections.

The proof will be shown in 3.1.2.

## Take-away messages

- (a) Algorithmic stability: similar dataset returns similar models
- (b) Stability implies generalization ( $\epsilon$ -uniform-stability)

$$\mathbb{E}_{D, \mathcal{A}} \mathbb{E}_L [L(\hat{\beta}) - \hat{L}(\hat{\beta})] \leq \epsilon,$$

All the slides will be available at [www.tengjiaye.com/generalization](http://www.tengjiaye.com/generalization) soon.



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Thanks!